

ALLFLEX 4131A

Maximum dexterity and sensitivity safety gloves for the most delicate handling

The seamless ALLFLEX gloves of Safety Jogger are designed for light and delicate applications for which a maximum of agility and sensitivity are an absolute must. Excellent for delicate assembly and other light handling. Nylon spandex liner with black micro foam nitrile coating for precision handling in dry conditions.

Performance level	4131A	
Liner	15 GAUGE NYLON + SPANDEX	
Coating	FOAM NITRILE	
Size range	EU 6-12	
Norms	ANSI/ISEA 105:2016	
	EN ISO 21420:2020	
	FN 388-2016	



















Industries:

Assembly, Automotive, Chemical, Cleaning, Construction, Logistics, Mining, Oil & Gas, Industry, Tactical



Performance level 4131A

EN388:2016	0	1	2	3	4	5
a. Abrasion resistance (cycles)	<100	100	500	2000	8000	-
b. Cut resistance (factor)	< 1.2	1.2	2.5	5.0	10.0	20.0
c. Tear resistance (newton)	< 10	10	25	50	75	-
d. Puncture resistance (newton)	< 20	20	60	100	150	-

EN ISO 13997 (TDM-100 test)	Α	В	C	D	E	F
e. Straight blade cut resistance (newton)		5	10	15	22	30

- a. Abrasion resistance: based on the number of cycles required to rub through the sample glove.
- b. Cut resistance: based on the number of cycles required to cut through the sample at a constant speed with a rotating blade.
- c. Tear resistance: based on the amount of force required to tear the sample.
- d. Puncture resistance: based on the amount of force required to pierce the sample with a standard sized point.
- e. Cut resistance according TDM100 test based on the number of cycles required to cut through the sample at a constant speed with a sliding blade.

High abrasion resistance

These gloves are built to withstand heavy use without wearing out quickly. They meet the highest level of abrasion resistance according to the EN 388 standard.

High dexterity

These gloves are made from the thinnest knit material available, ensuring the highest level of dexterity, comfort and protection.



Solutions for every workplace

INDUSTRIAL PROFESSIONAL TACTICAL TIGER GRIP

